|  |  |
| --- | --- |
| itr=25  #setting Input for inertial sensor  sigmaIMU=20;  AIMU=0.1;  sigmaDVL=5;  ADVL=0.1;  sigmaUSBL=5;  AUSBL=40; |  |
| itr=5  #setting Input for inertial sensor  sigmaIMU=20;  AIMU=0.1;  sigmaDVL=1;  ADVL=0.1;  sigmaUSBL=5;  AUSBL=40; |  |